

# Ch.3 Equilibrium

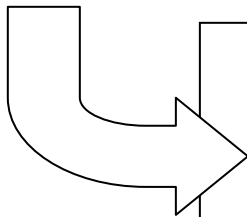
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A body is in equilibrium, the resultant of all forces (force + couple) acting on it is zero.

$$\vec{R} = \sum \vec{F} = 0 \qquad \vec{M} = \sum \vec{M} = 0$$

## 3/2 System isolation and the free-body diagram

Before applying the equilibrium conditions, it must be cleared which body or system are analyzed, and which forces act on the body.



### **Free-Body Diagram (FBD)** ☆

- The isolated system treated as a single body
- All forces acting on body are shown

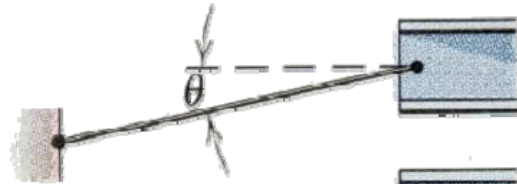
# Modeling the action of forces(1)

Type of contact

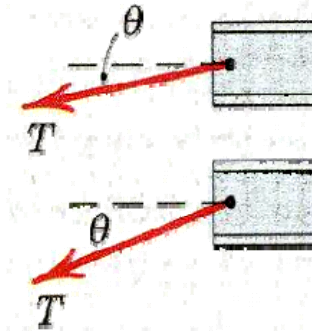
Action on body to be isolated

## 1. Flexible cable, belt, chain or rope

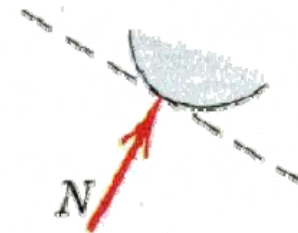
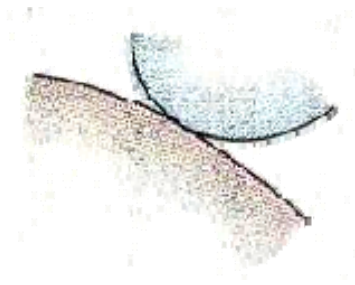
Weight negligible



Weight not negligible



## 2. Smooth surfaces



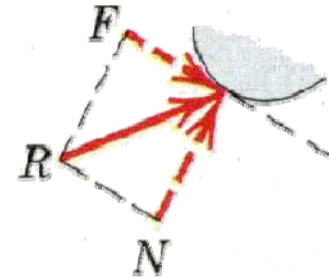
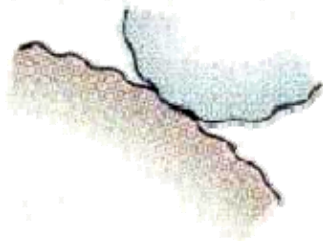
# Modeling the action of forces(2)

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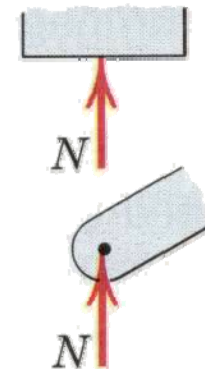
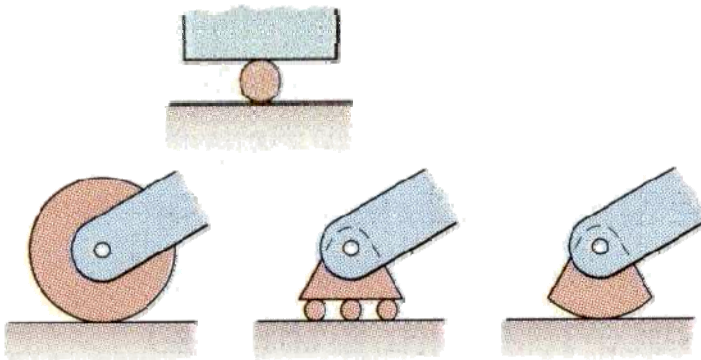
Type of contact

Action on body to be isolated

## 3. Rough surfaces



## 4. Roller support

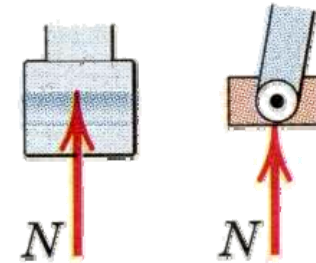
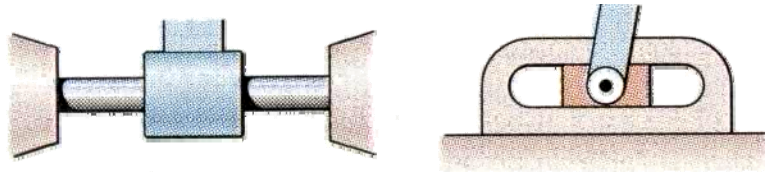


# Modeling the action of forces(3)

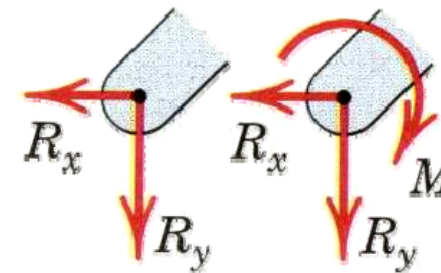
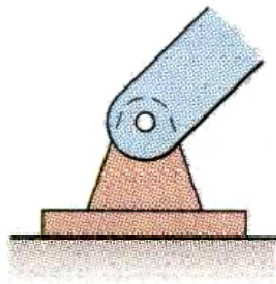
Type of contact

Action on body to be isolated

## 5. Freely sliding guide



## 6. Pin connection



Free to turn

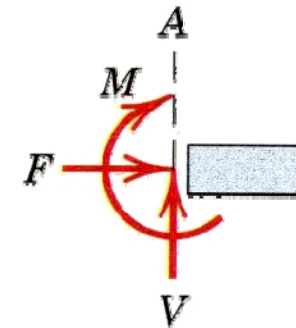
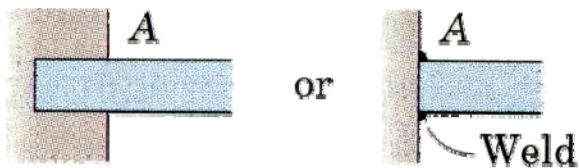
Not free

# Modeling the action of forces(4)

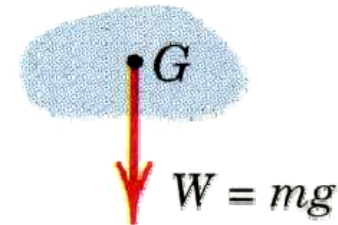
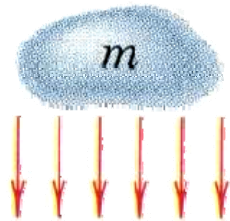
Type of contact

Action on body to be isolated

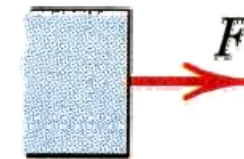
7. Built-in or fixed support



8. Gravitational attraction



9. Spring action



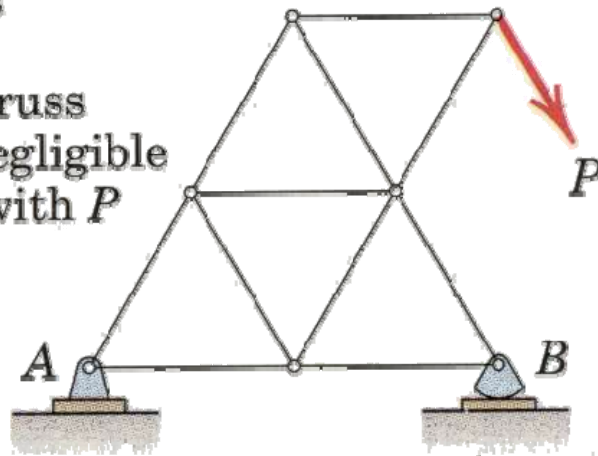
# Construction of FBD

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1. Choose a body to be isolated
2. Draw “complete external boundary” of the isolated body
3. Add all forces and moments
4. Indicate a coordinate system

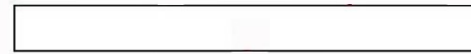
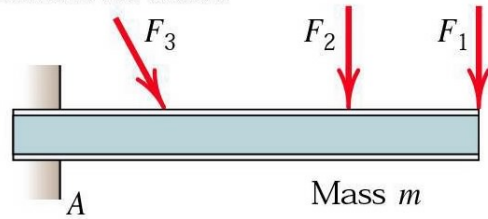
Plane truss

Weight of truss  
assumed negligible  
compared with  $P$

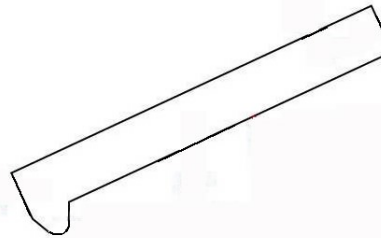
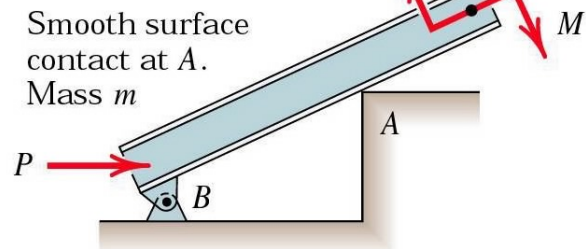


# Examples of FBD

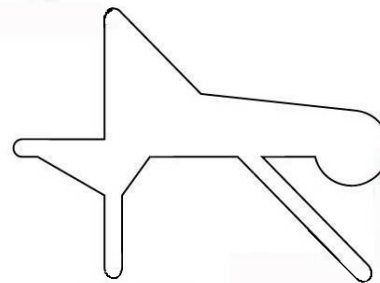
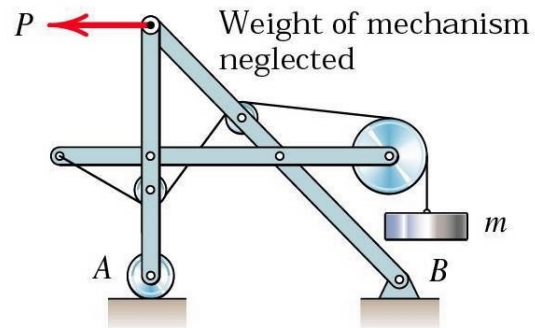
2. Cantilever beam



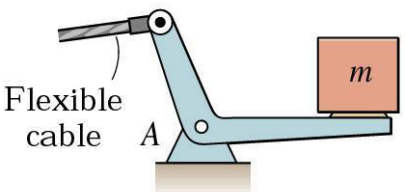
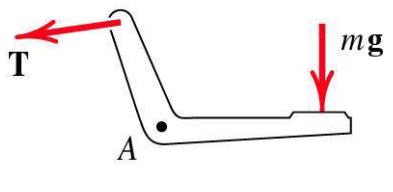
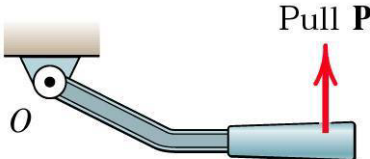
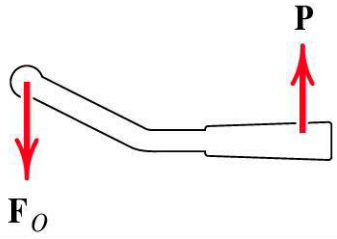
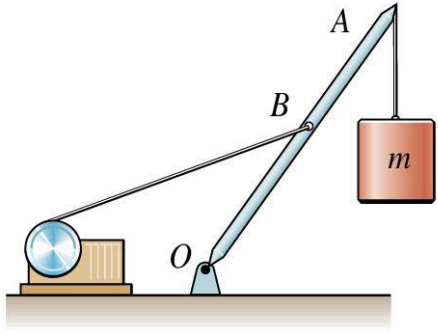
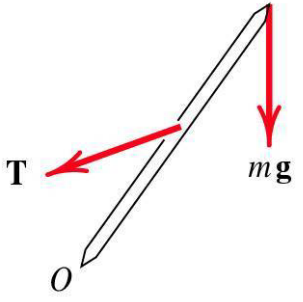
3. Beam



4. Rigid system of interconnected bodies analyzed as a single unit

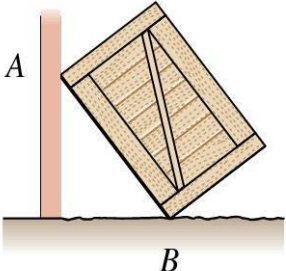
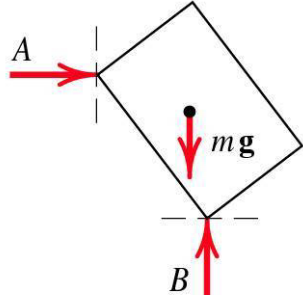
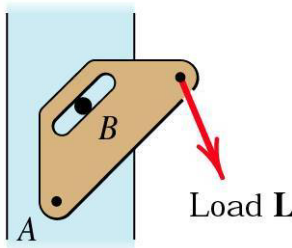
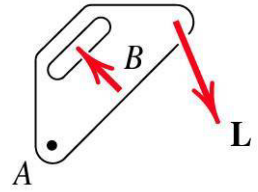


# FBD problem(1)

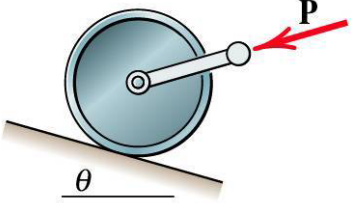
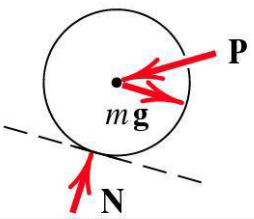
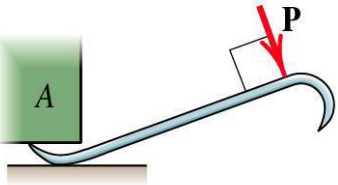
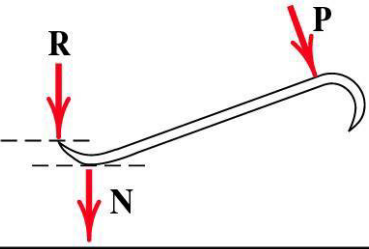
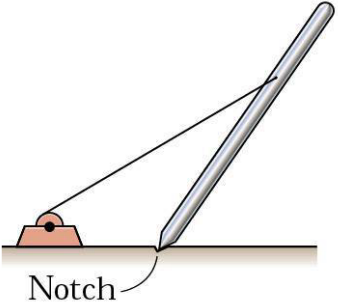
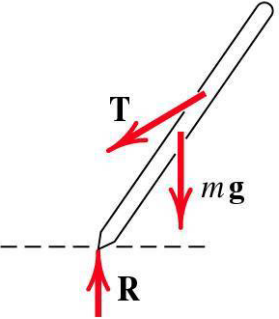
	Body	Incomplete <i>FBD</i>
1. Bell crank supporting mass $m$ with pin support at $A$ .		
2. Control lever applying torque to shaft at $O$ .		
3. Boom $OA$ , of negligible mass compared with mass $m$ . Boom hinged at $O$ and supported by hoisting cable at $B$ .		

# FBD problem(2)

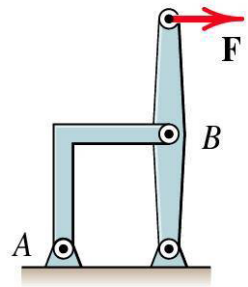
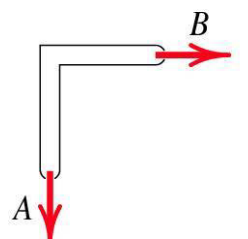
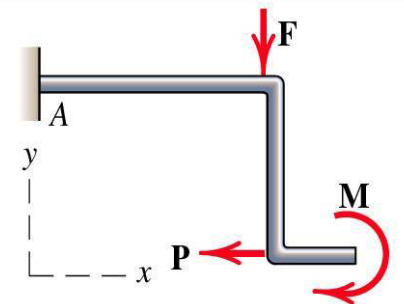
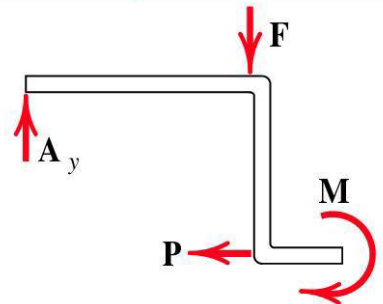
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	Body	Incomplete <i>FBD</i>
4. Uniform crate of mass $m$ leaning against smooth vertical wall and supported on a rough horizontal surface.		
5. Loaded bracket supported by pin connection at A and fixed pin in smooth slot at B.		

# FBD problem(3)

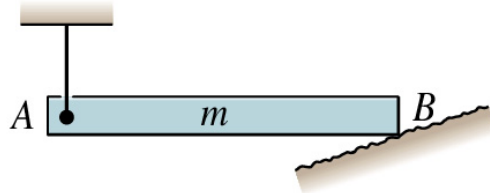
	Body	Wrong or Incomplete <i>FBD</i>
1. Lawn roller of mass $m$ being pushed up incline $\theta$ .		
2. Prybar lifting body A having smooth horizontal surface. Bar rests on horizontal rough surface.		
3. Uniform pole of mass $m$ being hoisted into position by winch. Horizontal supporting surface notched to prevent slipping of pole.		

# FBD problem(4)

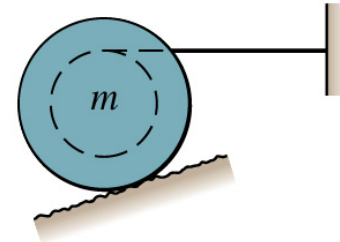
	Body	Wrong or Incomplete <i>FBD</i>
4. Supporting angle bracket for frame; Pin joints.		
5. Bent rod welded to support at A and subjected to two forces and couple.		

# FBD problem(5)

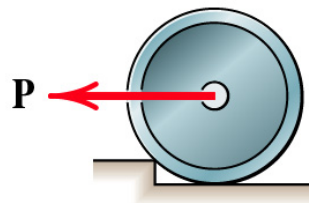
1. Uniform horizontal bar of mass  $m$  suspended by vertical cable at  $A$  and supported by rough inclined surface at  $B$ .



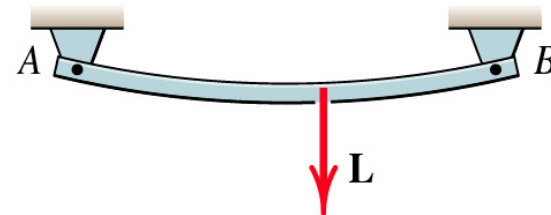
5. Uniform grooved wheel of mass  $m$  supported by a rough surface and by action of horizontal cable.



2. Wheel of mass  $m$  on verge of being rolled over curb by pull  $\mathbf{P}$ .

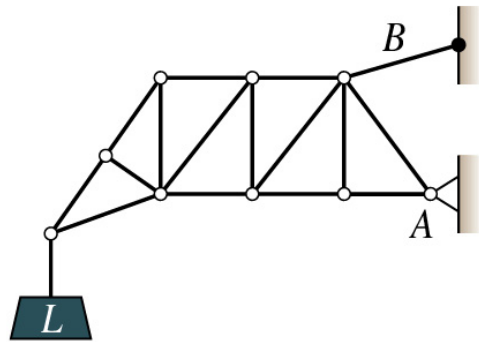


6. Bar, initially horizontal but deflected under load  $\mathbf{L}$ . Pinned to rigid support at each end.

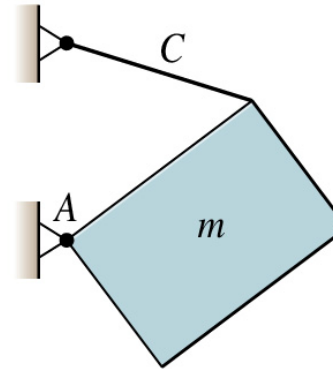


# FBD problem(6)

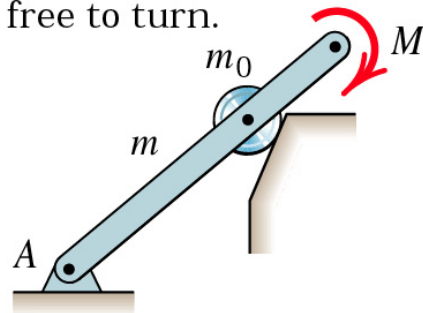
3. Loaded truss supported by pin joint at  $A$  and by cable at  $B$ .



7. Uniform heavy plate of mass  $m$  supported in vertical plane by cable  $C$  and hinge  $A$ .



4. Uniform bar of mass  $m$  and roller of mass  $m_0$  taken together. Subjected to couple  $M$  and supported as shown. Roller is free to turn.



8. Entire frame, pulleys, and contacting cable to be isolated as a single unit.

