

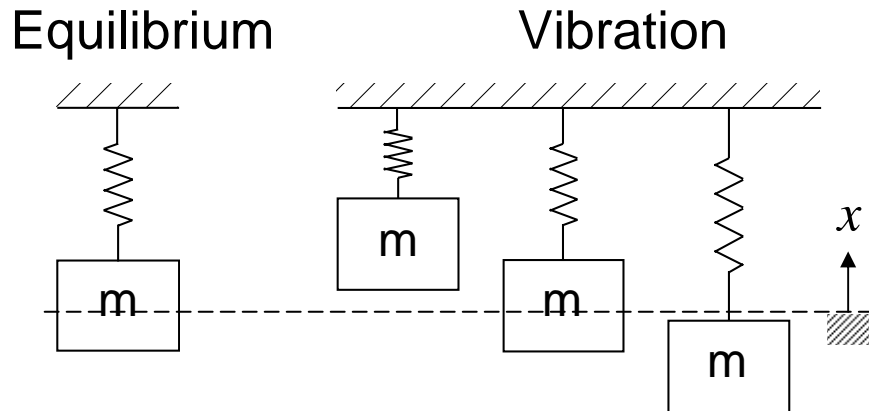
# Basic Concepts of Vibration

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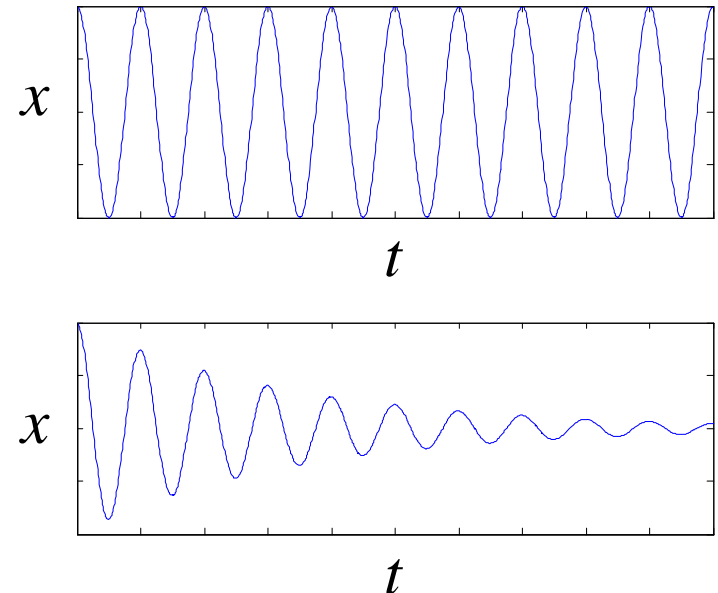
# What is Vibration?

**Vibration** is the study of the repetitive motion of objects relative to a stationary frame of reference or nominal position.

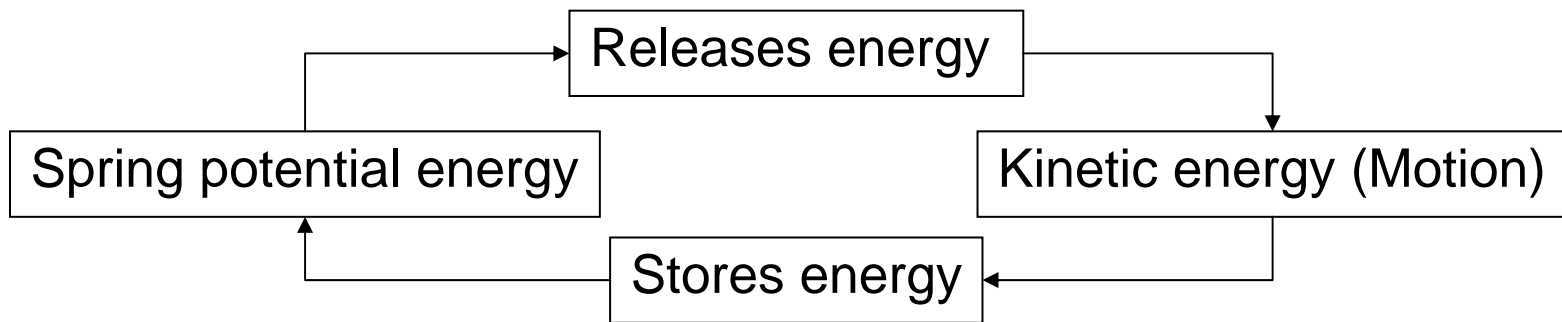
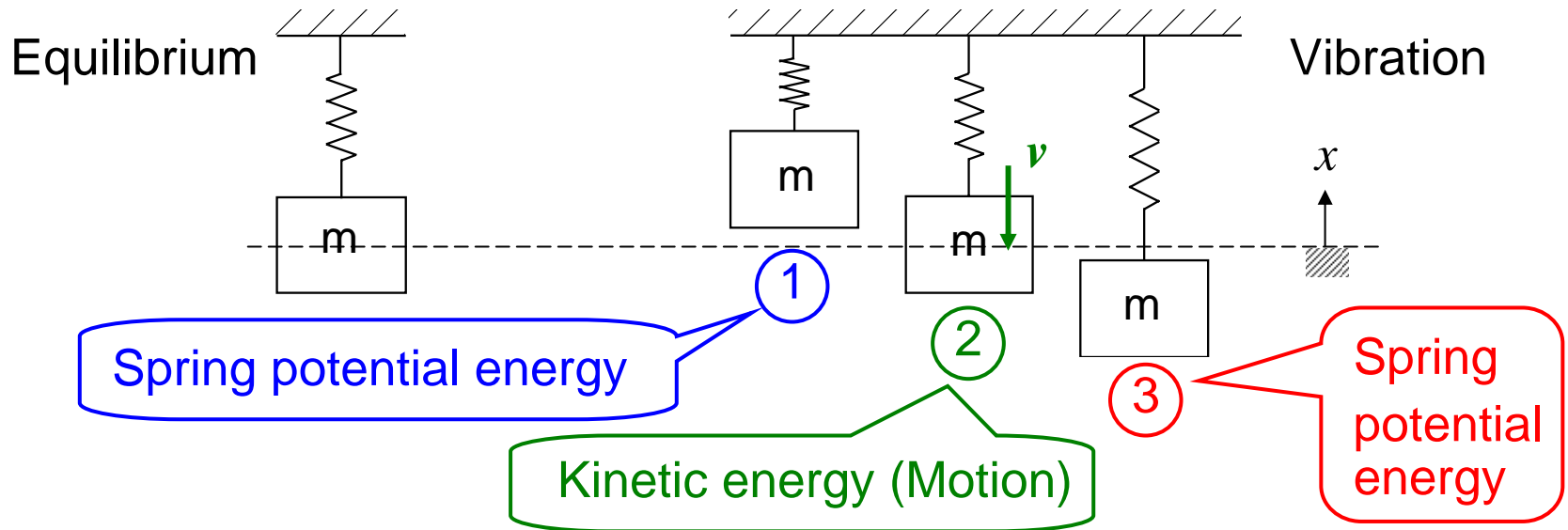
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vibration waveforms



# Physical Explanation



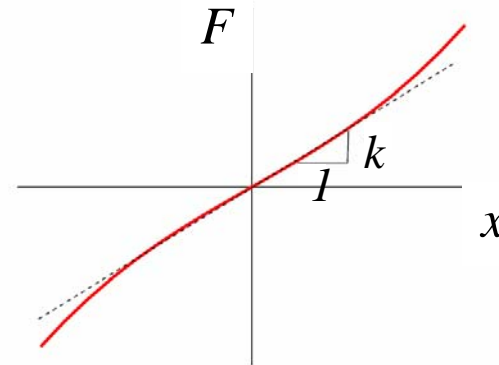
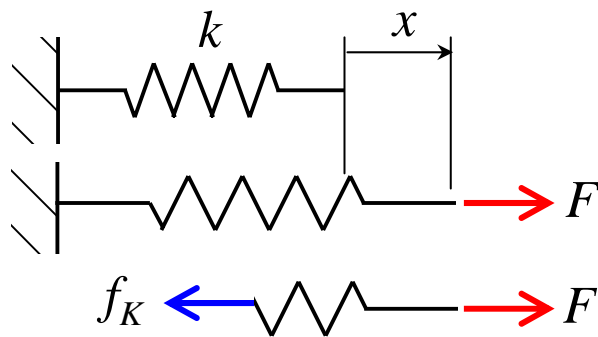
**A component that stores and release potential energy is required.**

# Elementary parts of vibrating systems (1)

## 1. Elastic components

Elastic components store or release potential (strain) energy as displacements increase or decrease.

e.g., helical spring, elastic bar & beam.



Restoring force

$$f_k = -F = -kx$$

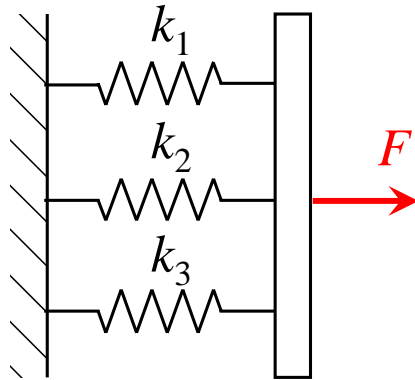
Potential energy

$$V = \int_0^x kx dx = \frac{1}{2} kx^2$$

# Elementary parts of vibrating systems (2)

## Combination of springs

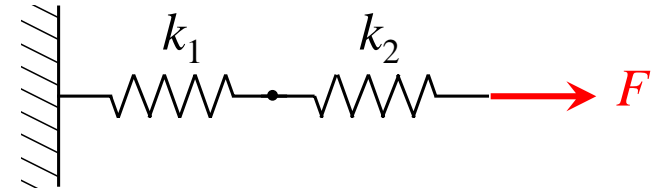
### Parallel



$$k_{eq} = k_1 + k_2 + k_3$$

$$k_{eq} = \sum_{i=1}^n k_i \quad n \text{ springs}$$

### Series



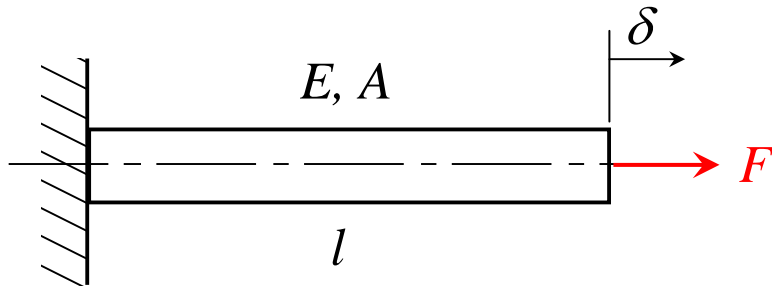
$$k_{eq} = \left( \frac{1}{k_1} + \frac{1}{k_2} \right)^{-1}$$

$$k_{eq} = \left( \sum_{i=1}^n \frac{1}{k_i} \right)^{-1} \quad n \text{ springs}$$

# Elementary parts of vibrating systems (3)

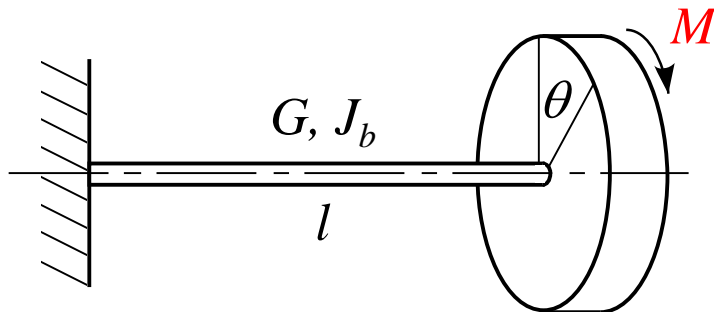
## Elastic elements as springs

### 1. Thin rod



$$k_{eq} = \frac{F}{\delta} = \frac{EA}{l}$$

### 2. Torsional bar

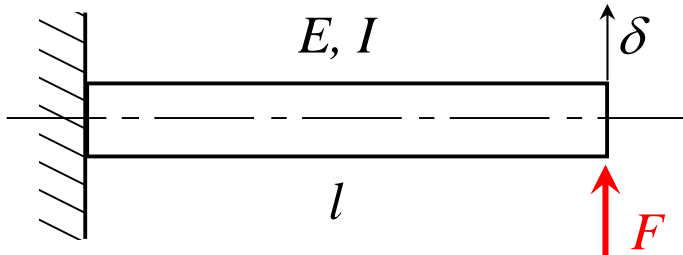


$$k_{eq} = \frac{M}{\theta} = \frac{GJ_b}{l}$$

# Elementary parts of vibrating systems (4)

Elastic elements as springs

## 3. Cantilever beam



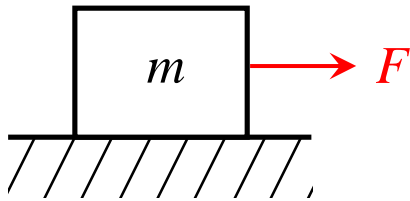
$$k_{eq} = \frac{F}{\delta} = \frac{3EI}{l^3}$$

# Elementary parts of vibrating systems (5)

## 2. Inertia (mass) components

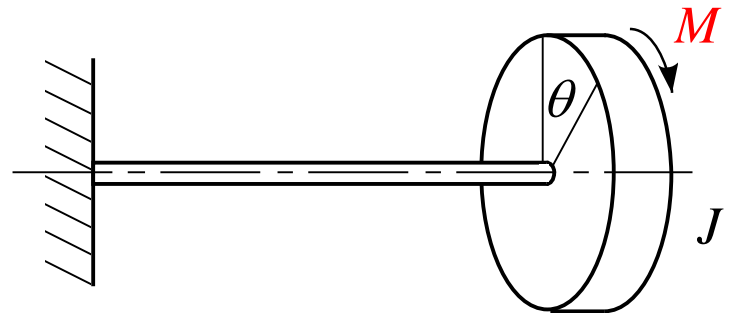
Inertia components store or release kinetic energy as velocities increase or decrease.

e.g., mass (translation), mass moment of inertia (rotation)



Kinetic energy (translation)

$$T = \frac{1}{2} m \dot{x}^2$$

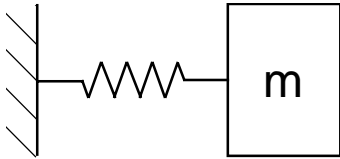


Kinetic energy (rotation)

$$T = \frac{1}{2} J \dot{\theta}^2$$

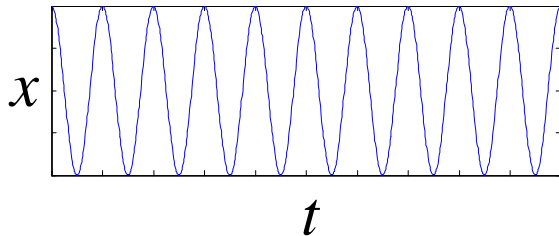
# Elementary parts of vibrating systems (6)

## Vibration of the spring-mass system



Ideal system

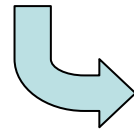
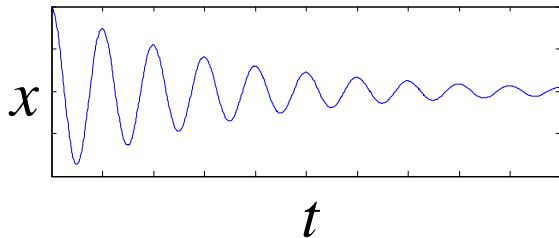
There is no energy loss during vibration.



The system will oscillate indefinitely.

Real system

Oscillating systems eventually die out and reduce to zero motion.

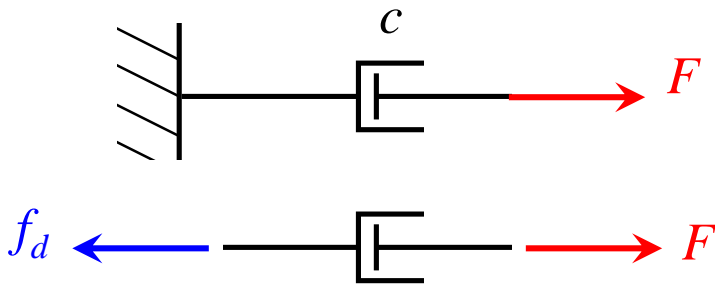


There is a component that dissipates energy.

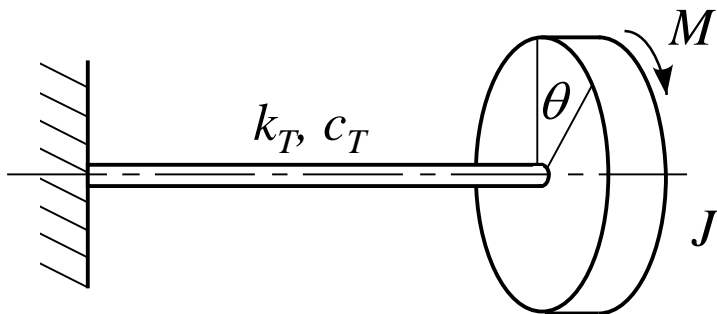
# Elementary parts of vibrating systems (7)

## 3. Viscous damper

Viscous damper or dashpot dissipates energy. Energy is converted to heat or sound.



$$f_d = -F = -c\dot{x}$$



$k, m, c$  for rotational motion

$$F_k = kx$$

$$F_d = c\dot{x}$$

$$F = m\ddot{x}$$

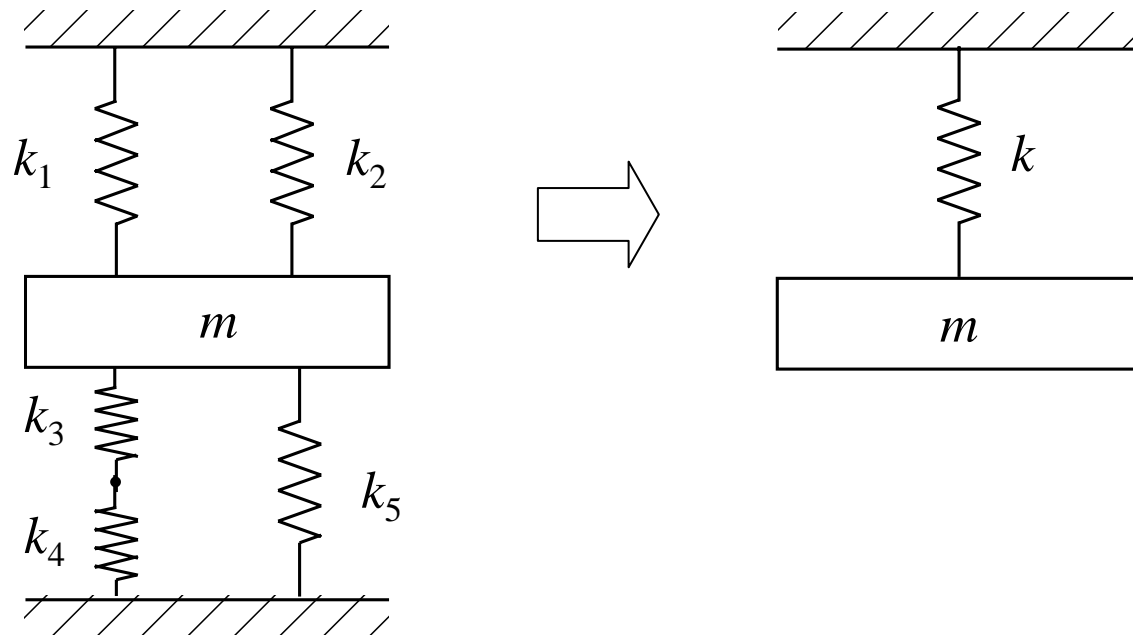
$$M_k = k_T\theta$$

$$M_d = c_T\dot{\theta}$$

$$M = J\ddot{\theta}$$

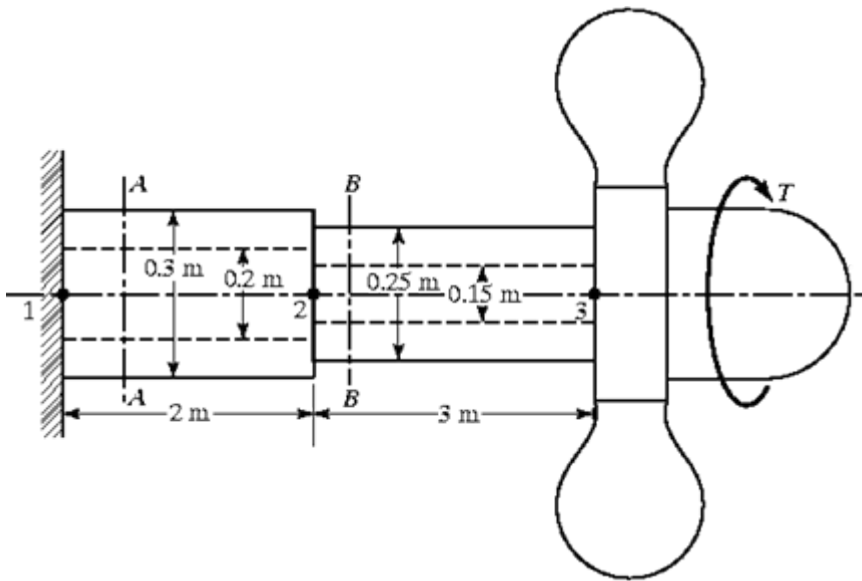
# Combination of springs (Example)

Find the equivalent single stiffness representation of the five-spring system shown in the figure.



# Springs (Example)

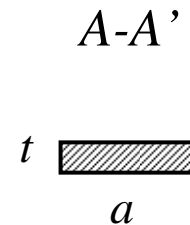
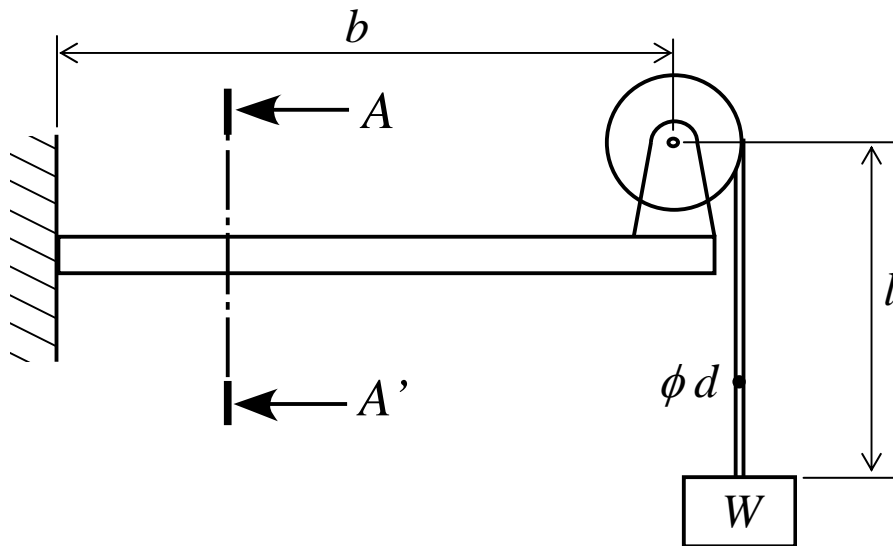
Determine the torsional spring constant of the steel propeller shaft shown in the figure. (Shear modulus  $G = 80 \text{ GPa}$ )



$$(k_{eq} = 6.6 \times 10^6 \text{ N-m/rad})$$

# Springs (Example)

A hoisting drum, carrying a steel wire rope, is mounted at the end of a cantilever beam as shown in the figure. Determine the equivalent spring constant of the system when the suspended length of the wire rope is  $l$ . Assume that the net cross-sectional diameter of the wire rope is  $d$  and the Young's modulus of the beam and the wire rope is  $E$ .



$$\left( k_{eq} = \frac{E}{4} \left( \frac{\pi a t^3 d^2}{\pi d^2 b^3 + l a t^3} \right) \right)$$